

Time	Theoretical trajectory location	Predicted location using RTPTP	% Error
0	5	-	
1	7	-	-
2	13	-	-
3	29	-	-
4	61	61	0
5	115	115	0
6	197	197	0
7	313	313	0
8	469	469	0
9	671	671	0
10	925	925	0

Table 1 Illustration of an example tracking (Example 1)



Time	Theoretical trajectory location	Predicted location using RTPTP	% Error
0	110	-	-
11	118	•	-
2	170	-	-
3	296		-
44_	526	526	0
5	890	890	0
6	1418	1418	
7	2140	2140	0
8	3086	3086	
9	4286	4286	0
10	5770	5770	0

Table 2 Illustration of a second example (Example 2)



RTPTP Reference System Configuration

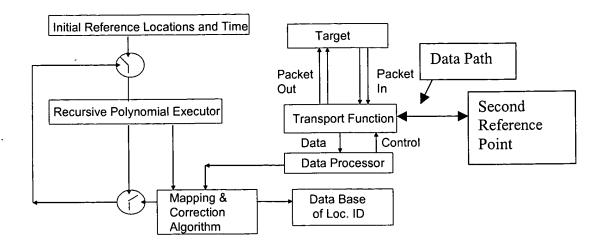


Fig. 3 RTPTP Reference System Configuration



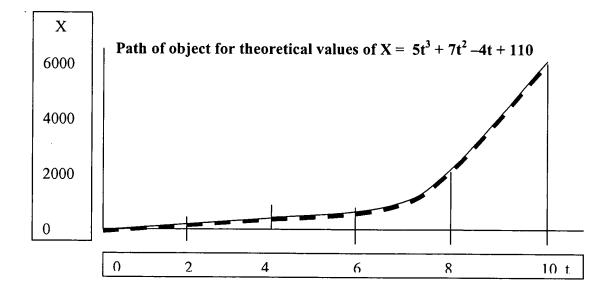


Fig. 1 Illustration of High Accuracy of RTPTP Algorithm (The true path and predicted RTPTP path coincide as above)

True Path			
Predicted Path	_	_	



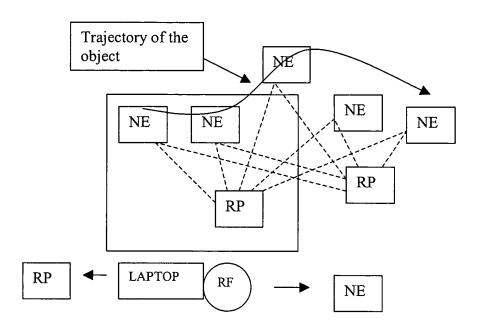


Fig. 2 Illustration of object tracking

RP – Reference Point with RTPTP Geometric Pairing Technology NE – Network Element (or Object) in the Theater